# CG-5100 IMU

## emcore

#### **EMCORE's Commercial Inertial Measurement Unit Solution**



#### **Key Features**

- EMCORE's patented Digital Signal Processing (DSP) FOGs for high reliability and stable performance
- Highly accurate rate and acceleration data
- Designed to meet COTS requirements
- Measures roll, pitch, and yaw angular rates and accelerations
- · Fiber optic gyro stability
- Affordable, compact design
- Excellent shock and vibration performance

#### **Applications**

- Antenna, optical, and camera stabilization
- GPS augmentation
- Autonomous vehicles
- Drilling
- Navigation
- Motion sensing

### CG-5100 – The Complete Position, Velocity, and Attitude Solution

The versatile EMCORE CG-5100 Inertial Measurement Unit (IMU) combines proprietary technologies – highly accurate fiber optic gyro (FOG)-based sensors coupled with industry proven MEMS accelerometers – all within a compact single enclosure, providing reliability and long-term compliance to customer specifications. Through its seamless integration of these two highly reliable navigation components, the CG-5100 provides a ground-breaking low-cost, small form factor solution for inertial measurement.

The EMCORE sensor engine of FOGs and accelerometers creates a flexible and efficient IMU, a high performance motion sensing package ideally suited for critical sensing applications and GPS integrated navigation programs. This strapdown inertial subsystem offers outstanding reliability and accurate 6-degreesof-freedom measurement. The CG-5100 achieves its excellent performance by employing proprietary algorithms to a fully digital gyro

sensor output, enabling the system to characterize and correct for the effects of temperature and misalignment. The CG-5100 also affords the end user with a convenient and easy to adapt output in a fully digital RS-232/RS-422 format.





The CG-5100 technology is ideal for precise positioning, even in challenging environments.

#### EMCORE CG-5100 Fiber Optic Gyro IMU

Performance Specifications		
Input Rate (max)	±375°/sec	
Bias Instability (25°C)	≤1°/hr, 1σ	
Bias vs. Temperature ( $\leq 1$ °C/min)	≤ <b>6°/hr, 1</b> σ	
Bias Offset (25°C)	±20°/hr	
Scale Factor Non-linearity (max rate, 25°C)	≤1000 ppm, 1 $\sigma$	
Scale Factor vs. Temperature ( $\leq 1  ^{\circ}C/min$ )	≤500 ppm, 1 $\sigma$	
Angle Random Walk (25°C)	≤0.067°/√hr (≤4°/hr/√Hz)	
Bandwidth (-3 dB)	≥100 Hz	

#### Electrical/Mechanical

Initialization Time (valid data)	≤5 secs	
Data Interface	Asynchronous RS-422 or RS-232	
Baud Rate	115.2 Kbps	
Data Rate	100 Hz	
Dimensions (max)	169.4 mm L x 152.4 mm W x 88.9 mm H (6.67" x 6" x 3.5")	
Weight (max)	2.27 kg (5 lbs)	
Power Consumption	15 W	
Input Voltage	+9 to +18 VDC	

Environment		
Temperature (operating)	-40°C to +65°C (-40°F to +149°F)	
Shock (operating)	7 g, 11 msec, half-sine	
Vibration (operating)	8 g rms, 20-2000 Hz, random	

Accelerometers		
Input Limit (max)	±10 g	
Bias Instability (constant temp)	<0.25 mg, 1σ	
Scale Factor Temperature Sensitivity	1000 ppm/°C, 1σ	
Velocity Random Walk (25°C)	≤0.12 mg/√Hz (0.23 ft/sec/√hr)	
Bandwidth (-3 dB)	50 Hz <b>±5%</b>	

For detailed interface control drawings (ICD) and technical manuals on this product, please visit **emcore.com/nav/support** 











Mounting: Utilize (x4) 1/4 x 20 socket head cap screws – torque to 75 in-lbs max.



EMCORE's CG-5100 is ideal for autonomous vehicle applications

#### For More Information

+1 866.234.4976 | emcore.com/nav | navigation-sales@emcore.com

EMCORE Corporation 2015 Chestnut Street, Alhambra, CA U.S.A. ▶+1 626.293.3700 ►+1 626.293.3429



©2022 EMCORE Corporation. Specifications subject to change without notice. EMCORE and PIC Inside are trademarks of EMCORE Corporation.