MTi-2

- Miniature form factor (12x12 mm)
- Easy integration
- Development Kit available

The MTi-2 is a self-contained Vertical Reference Unit (VRU) as a 12.1 x 12.1 mm module. The Xsens optimized strapdown algorithm (AttitudeEngineTM) performs high-speed dead-reckoning calculations at 1 kHz allowing accurate capture of high frequency motions. Xsens' industry-leading sensor fusion algorithm provides high accuracy and sensor auto-calibration in a cost-effective module for a wide range of (embedded) applications. It relieves users from the design, integration and maintenance of gyroscopes, accelerometers and other sensors.

The MTi-2 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.

Sensor fusion performance

Sensor rusion performance	
Roll, Pitch	0.5 deg RMS
Yaw/Heading	unreferenced, low drift
Strapdown Integration (SDI)	Yes
Gyroscope	
Standard full range	2000 deg/s
In-run bias stability	6 deg/h
Bandwidth (-3dB)	230 Hz
Noise Density	0.003 ⁰/s/√Hz
g-sensitivity (calibr.)	0.001 º/s/g
Accelerometer	
Standard full range	16 g
In-run bias stability	40 µg
Bandwidth (-3dB)	230 Hz
Noise Density	70 µg/√Hz
Magnetometer	
Standard full range	+/- 8 G
Total RMS noise	0.5 mG
Non-linearity	0.2%
Resolution	0.25 mG
GNSS Receiver	
GNSS receiver interface	n/a
GNSS precision	n/a
RTCM input port	n/a
Barometer	
Barometer interface	n/a



• 3D models available on request

• Available online via Digi-Key, Mouser, Farnell and local distributors

Mechanical	
Mechanica	
IP-rating	IP00
Operating Temperature	-40 to 85 °C
Casing material	PCB
Mounting orientation	No restriction, full 360° in all axes
Dimensions	– 12.1 x 12.1 x 2.55 mm
Connector	SMD, footprint compatible with
	JEDEC PLCC-28
Weight	— 0.6 g
Certifications	CE, FCC, RoHS
Electrical	
Input voltage	– 2.8 to 3.6V
Power consumption (typ)	<100 mW @ 3V
Interfaces / IO	
Interfaces	UART, SPI, I ² C
Sync Options	Yes
Protocols	– Xbus
Clock drift	10 ppm or external
Output Frequency	Up to 1 kHz
Built-in-self test	Gyr, Acc, Mag
Software Suite	
GUI (Windows/Linux)	MT Manager Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
	public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals,
	community and knowledge base





Unless stated otherwise, all specifications are typical. Specifications subject to change without notice.