

## Multi-Frequency, Multi-Constellation Centimeter-Accurate GNSS

The Piksi Multi GNSS Receiver from Swift Navigation. Its dual-frequency operation offers fast RTK convergence times and reliable, centimeter-accurate results at a breakthrough price.

## CENTIMETER-LEVEL ACCURACY

Autonomous systems require precision navigation—especially those that perform critical functions. Swift Navigation solutions utilize real-time kinematic (RTK) technology, providing location solutions that are 100 times more accurate than traditional GPS.

## FAST CONVERGENCE TIMES

Multiple signal bands enable faster convergence times to high-precision mode. Single band RTK systems converge in minutes, while Piksi Multi converges to a high-precision solution within seconds. This allows for much faster system start times, as well as faster reacquisitions, which is critical to robotic systems.

#### **ROBUST POSITIONING PERFORMANCE**

Piksi Multi supports GPS L1/L2, GLONASS G1/G2, BeiDou B1/B2, Galileo E1/ E5b for RTK measurements and positioning and SBAS for robust sub-meter positioning in non-RTK mode. Additional constellations create more robust positioning performance in a variety of challenging skyview environments. Integrated MEMS oscillator technology enhances robustness under vibration and shock. An onboard 6DOF, MEMS based inertial measurement unit allows customers to develop their own sensor fusion algorithm that enhances the positioning performance of Piksi Multi.

## **RAPID PROTOTYPING**

Piksi Multi is designed to be easy to use. The Piksi Multi Evaluation Kit includes: 2 Piksi Multi GNSS Receivers; 2 integrator-friendly Evaluation Boards; 2 GNSS survey grade antennas; 2 powerful radios and integration accessories. Piksi Multi features multiple high-density I/O connectors, providing a smooth and simple integration experience.

## **BREAKTHROUGH PRICE**

Swift Navigation is built on the notion that highly-precise RTK solutions should be offered at an affordable price. Piksi Multi embraces the foundation of unmatched affordability and is available at a much lower cost than comparable systems.



## BENEFITS

- Fast RTK Convergence Times
- Highly-Competitive Pricing
- Easy Integration into a Variety of Applications
- Future-Proof Hardware with In-Field Software Upgrades
- Onboard Linux Allows Flexibility

## **FEATURES**

- Dual Frequency and Multi Constellation
- Up to 10 Hz Solution Rates
- Advanced MEMS Oscillator Technology
- Raw IMU Data Stream from the On-Board MEMS IMU
- Flexible Interfaces Including UART, Ethernet, CAN<sup>5</sup> and USB

# Piksi Multi

## **GNSS** Characteristics

#### **GNSS Signal Tracking**

GPS L1/L2, GLONASS G1/G2, BeiDou B1/B2, Galileo E1/E5b SBAS<sup>1</sup>

## **GNSS Data Rates**

Measurements (Raw Data)	Up to 10 Hz
Standard Position Outputs	Up to 10 Hz
<b>RTK Position Outputs</b>	Up to 10 Hz <sup>2</sup>
Swift Binary Protocol (SBP) and NMEA-0183	

#### Maximum Operating Limits<sup>3</sup>

Ve	locity

## **Position Performance** Specifications

#### **Position, Velocity & Time Accuracy**

Horizontal Position Accuracy (CEP 50 in SBAS Mode) 0.75 m <sup>8</sup>	
Velocity Accuracy	0.03 m/s RMS
Time Accuracy	60 ns RMS
Real Time Kinematic (RTK Accuracy 1ơ)	
- Horizontal	0.010 m + 1 ppm
- Vertical	0.015 m + 1 ppm
RTK Initialization Parameters	
- Initialization Time	< 10 s
- Initialization Reliability	> 99%
- Solution Latency	< 30 ms

#### Time to First Fix (TTFF) Specifications<sup>8</sup>

Hot Start <sup>9</sup>	Cold Start <sup>10</sup>	Reacquisition <sup>11</sup>
< 5 s	< 60 s	< 2 s

## Communication

Navigation Outputs	SBP and NMEA 0183 (Configurable)
Reference Inputs / Outputs	RTCM 3.x
Network Protocol Supported	NTRIP Client

## Electrical & I/O

Power	
Input Voltage	5 - 15 V DC
Typical Power Consumption	2.9 W <sup>4</sup>
Antenna LNA Power Specifications	
Output Voltage	4.85 V DC
Max Output Current	100 mA
Connectors	
1 x 20 Pin SAMTEC Connector (PN: TMM-110-03-F-D)	
2 x 60 Pin High Density Connectors (PN: 61082-061400LF)	
1 x MMCX Female Antenna Port	
Communication Interfaces	
2 x UART-LVTTL Ports (1 Mbps)	
2 x CAN⁵ Bus (1 Mbps)	
Ethernet support up to 100Mbps	
2 x USB 2.0 (1 Device, 1 Host)	

## Actual Size

515 m/s



## **Physical & Environmental**

Dimensions <sup>6</sup>	48 mm x 71 mm x 12.4 mm Form factor compatible with common GNSS modules
Weight	26 g
Temperature <sup>7</sup>	
Operating	-40° C to +85° C
Storage	-40° C to +85° C
Humidity	95% non-condensing as measured by MIL-STD-810G, Method 507.5 Procedure II
Vibration (Operating	and Survival)
Random	MIL-STD 810G, Method 514.6 (Category 24, 7.7 g RMS)
Sinusoidal	IEC 60068-2-6 (Test Fc–5g)
Mechanical Shock	
Operating	MIL-STD 810G, Method 516.6, Procedure I (40 g)
Survival	MIL-STD-810G, Method 516.6

## **Packaging & Accessories**

#### Visit the Swift online store at www.swiftnav.com

#### Piksi Multi Evaluation Kit

Designed to provide a seamless easy-to-use RTK positioning experience through a single kit consisting of 2 Piksi Multi GNSS Receivers; 2 Evaluation Boards; 2 GNSS survey grade antennas; 2 powerful radios and all other required integration accessories.

Procedure V (75 g)

#### Piksi Multi GNSS Receiver Pack

Quick integration packs designed both for customers seeking to create custom RTK solutions for unique projects or for seasoned RTK systems integrators.

## Piksi Multi GNSS Receiver

Designed for the experienced systems integrator and the large volume enterprise customer.

- SBAS Support includes the United States-based Wide Area Augmentation Systems (WAAS), the pan-European Union-based European Geostationary Navigation Overlay Navigation System (EGNOS), the Japanese Multifunctional Transport Satellites (MTSAT) Satellite Augmentation System (MSAS) providing coverage for Japan and Australia and the GPS-Aided GEO Augmented Navigation (GAGAN) regional system operated by the Indian government. Current firmware supports 10Hz GPS L1/L2, GLONASS G1/G2, BeiDou B1/B2, Galileo E1/E5b low-latency RTK positioning or 5 Hz GPS L1/L2, GLONASS G1/G2, BeiDou B1/B2, Galileo E1/E5b time matched RTK positioning.
- 3 As required by the U.S. Department of Commerce to comply with export licensing restrictions.
  - Typical power consumption by module in RTK positioning mode.
- 5 The CAN implementation Bus on Piksi Multi is currently hardware ready and is electrically verified. We do not support any specific CAN output protocol (e.g. J1939) and have no immediate plans to do so.
  A hardware update on the Piksi Multi to use a higher grade CPU with better thermal characteristics was implemented, resulting in 0.4mm height
- increase of the Piksi Multi. Contact customer support for more information on this.
- 7 The use of an on-board heat sink is required in applications where ambient temperatures exceed 65°C. The receiver board ships with a provided heat sink attachment.
- 8 In open sky and strong signals conditions.
- 9 Hot Start is the time taken by the receiver to achieve a standard position fix after a brief outage. For example, the time taken to fix a position for a car that is exiting a long tunnel. This can also be simulated by a simple RF on/off test with outages between 30 and 50 seconds
- 10 Cold Start is the time taken by the receiver to achieve a standard position fix after a prolonged outage. For example, the time taken to achieve a position fix for a car that has been parked overnight in a garage and once it sees the sky view for the first time.
- 11 Re-acquisition is defined as the time taken to re-acquire position lock after brief moment of outage. For example, a car traveling under a freeway/ highway overpass. This can also be simulated by a simple RF on/off test with outages between 1 and 5 seconds.

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