



OEM-IMU-STIM300

Commercial MEMS IMU combines with SPAN GNSS+INS technology from Hexagon | NovAtel to deliver 3D position, velocity and attitude

Deeply-coupled GNSS+INS technology

SPAN GNSS+INS technology brings together two different but complementary technologies: Global Navigation Satellite System (GNSS) positioning and Inertial Navigation Systems (INS). The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) measurements combine to provide an exceptional 3D navigation and attitude solution that is stable and continuously available, even through periods when satellite signals are blocked.

Low noise commercial MEMS

The STIM300 is a Micro Electromechanical System (MEMS) IMU from Sensonor. It features low noise gyros and accelerometers in a small, lightweight, environmentally sealed enclosure. The STIM300 enables precision measurements for applications that require low cost, high performance and rugged durability in a very small form factor. When integrated with SPAN GNSS+INS technology, this IMU is ideal for airborne and ground applications that require accurate 3D position, velocity and attitude (roll, pitch and azimuth) data.

Combining SPAN and MEMS technology

A proprietary NovAtel MEMS Interface Card (MIC) couples the STIM300 with SPAN enabled receiver cards, offering a unique, powerful GNSS+INS system for weight and size constrained applications. Designed as a board stack configuration for ease of integration, the MIC interfaces directly with NovAtel's small form factor OEM719 receiver.

Require higher accuracy?

Receivers from NovAtel provide your choice of accuracy and performance, from decimetre to RTK-level positioning. For more demanding applications, Waypoint Inertial Explorer post-processing software offers the highest level of accuracy.



Benefits

- Ideal for size constrained applications
- Easy integration with NovAtel's SPAN capable GNSS+INS receivers
- Commercially exportable
- Low 5.0 VDC power input

Features

- Low noise commercial grade gyros and accelerometers
- Small size and lightweight
- IMU data rate: 125 Hz
- Direct UART interface to OEM7 receivers
- SPAN GNSS+INS capability with configurable application profiles

OEM-IMU-STIM300 Product Sheet

SPAN System Performance¹

Horizontal Position Accuracy (RMS)

Single point L1/L2	1.2 m			
SBAS ²	60 cm			
DGPS	40 cm			
TerraStar-L ^{3,4}	40 cm			
TerraStar-C PRO ^{3,4}	2.5 cm			
TerraStar-X ^{3,4}	2 cm			
RTK	1cm +1ppm			
Data Rates				
IMU Raw Data Rate	125 Hz			
INS Solution	Up to 200 Hz			
Time Accuracy ⁵	20 ns RMS			

Max Velocity⁶ 515 m/s

IMU Performance⁷

Gyroscope Performance

Input range In-run bias stability Angular random walk

±400 deg/sec 0.5 deg/hr 0.15 deg/√hr

Accelerometer Performance

Range ±10 g In-run bias stability 0.06 m/s/√hr Velocity random walk

0.05 mg

Physical and Electrical

IMU dimensions $39 \times 45 \times 22 \text{ mm}$

IMU weight 55 g

Power

Input voltage +5.0 VDC Power consumption 1.5 W

Communication Interface RS-422 UART

Environmental

Temperature

Operating Storage

-40°C to +85°C -55°C to +90°C

Performance During GNSS Outages⁸

Outage Duration	Positioning Mode	Position Accuracy (M) RMS		Velocity Accuracy (M/S) RMS		Attitude Accuracy (Degrees) RMS		
		Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK ⁹	0.02	0.03	0.020	0.010	0.015	0.015	0.080
	PPP	0.06	0.15					
	SP	1.00	0.60					
	Post-Processed ¹⁰	0.01	0.01	0.020	0.010	0.007	0.007	0.022
10 s	RTK ⁹	0.27	0.13	0.055	0.017	0.025	0.025	0.095
	PPP	0.31	0.25					
	SP	1.25	0.70					
	Post-Processed ¹⁰	0.02	0.02	0.020	0.010	0.007	0.007	0.022
60 s	RTK ⁹	6.52	1.43	0.280	0.055	0.045	0.045	0.130
	PPP	6.56	1.55					
	SP	7.50	2.00					
	Post-Processed ¹⁰	0.26	0.10	0.024	0.011	0.009	0.009	0.024

1 Typical values. Performance specifications subject to GNSS system characteristics, Signal-in-Space (SIS) operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference. 2. GPS-only. 3. Requires a subscription to TerraStar data service. Subscriptions available from NovAtel. 4. TerraStar service available depends on the SPAN enabled receiver used. See the receiver product sheet for details. 5. Time accuracy does not include biases due to RF or antenna delay. 6. Export licensing restricts operation to a maximum of ST6 metres/second. 7. Supplied by IMU manufacturer. 8. Outoge statistics were calculated by taking the RMS of the maximum errors over a minimum of 30 complete GNSS outsges. Each outage was followed by 120 seconds of full CNSS ovailability before the next outage was applied. High accuracy GPS updates (fixed ambiguities) were available before and after each outage. The survey date used to generate these statistics is ground vehicle data collected with frequent changes in azimuth (i.e. as normally the survey date used to generate these statistics is ground vehicle data collected with frequent changes in azimuth (i.e. as normally the survey data used to generate these statistics is ground vehicle data collected with frequent changes in azimuth (i.e. as normally the survey data used to generate these statistics is and vehicle data collected with frequent changes in azimuth (i.e. as normally the survey data used to generate these statistics) are collected with frequent changes in azimuth (i.e. as normally the survey data used to generate these statistics) are collected with frequent changes in azimuth (i.e. as normally the survey data used to generate the survey d observed in ground vehicle environments). 9.1 ppm should be added to all values to account for additional error due to baseline length. 10. Post-processing accuracy using Inertial Explorer processing software. The survey data used to generate these statistics is ground vehicle data collected with frequent changes in azimuth (i.e., as normally observed in ground vehicle environments).

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