

Vector[™] VS330 GNSS Receiver

PROFESSIONAL POSITIONING AND HEADING RECEIVER





Experience the Vector[™] VS330 with our powerful Athena GNSS core engine technology. The Vector VS330 supports precise marine, dynamic positioning, and land applications that require RTK positioning and precise heading performance.

The Vector VS330 use all of the innovations in Hemisphere GNSS' Eclipse[™] Vector technology. Our optimized Eclipse Vector technology brings a series of new features to the Vector VS330 including heave, pitch, and roll output, and more robust positioning and heading performance.

The Vector VS330 receiver, with its display and user interface, can be conveniently installed near the operator. The two antennas are mounted separately with a user-determined separation to meet the desired heading accuracy. The fullysubscribed Vector VS330 uses Atlas L-band, Beacon, and SBAS for differential positioning. Our firmware allows the VS330 to transition smoothly between DGNSS systems.

Key Features

- Athena™ RTK, Atlas[®] L-band, Beacon and SBAS capable
- Extremely accurate heading with baselines up 50 m
- Multi-frequency GPS/GLONASS/BeiDou RTK capable
- Automatic antenna baseline survey
- Maintain heading and position lock when more of the sky is blocked
- Runs Athena core GNSS engine offering improved initialization times, robustness in difficult environments, performance over long baselines and under scintillation
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites

GNSS Receiver Specifications

Vector GNSS L1/L2 RTK Receiver **Receiver Type:** Signals Received: GPS, GLONASS, BeiDou, and Atlas Channels: 502 **GPS Sensitivity**: -142 dBm SBAS Tracking: 3-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional Timing (1 PPS) Accuracy: 20 ns Rate of Turn: 100°/s maximum **Compass Safe** 30 cm (with enclosure) ⁵ Distance: Cold Start: 60 s (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) 10 s typical (almanac, RTC and position) Hot Start: **Heading Fix:** 10 s typical (valid position) Antenna Input Impedance: 50 O Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft) Differential SBAS, Beacon, External RTCM, Atlas **Options:** L-band and Athena RTK

ACCUIACY		
Positioning:	RMS (67%)	2DRMS (95%)
Single Point: 1	2.4 m	
SBAS: ²	0.6 m	
Atlas H10: 6	0.08 m	0.16 m
Atlas H30: 6	0.3 m	
Atlas Basic: 6	0.5 m	
RTK: 1, 3	10 mm + 1 ppm	20 mm + 2 ppm
Heading (RMS):	0.2° @ 0.5 m antenna separation	
	0.1° @ 1.0 m antenna separation	
	0.05° @ 2.0 m antenna separation 0.02° @ 5.0 m antenna separation	
	0.01° @ 10.0 m antenna separation	
Pitch/Roll (RMS):	10	·
Heave (RMS):	30 cm (DGPS) ⁵ ,10 cm (RTK) ^{1,3}	
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Beacon Receiver Specifications

Channels: 2-channel, parallel tracking Frequency Range:283.5 to 325 kHz Operating Modes: Manual, Automatic, and Database Compliance: 5 kHz

L-Band Receiver Specifications

Receiver Type:Single ChannelChannels:1530 to 1560 MHzSensitivity:-130 dBmChannel Spacing:5 kHzSatellite Selection:Manual or AutomaticReacquisitionInformationTime:15 sec (typical)

Communications

Accuracy

 Ports:
 2 full-duplex RS232, 1 half-duplex RS422 port 1 USB-A

 Baud Rates:
 4800 - 115200

 Correction I/O
 Hemisphere GNSS proprietary ROX format, RTCM v2.3, RTCM v3.2, CMR⁷, CMR⁺⁷

 Data I/O Protocol:
 NMEA 0183, Hemisphere GNSS binary ⁶ 1 PPS (active high, rising edge sync, 10 kΩ, 10 pF load)

Power Input Voltage:	8-36 VDC	
Power Consumption:	5.3 W nominal (GPS L1/L2 + GLONASS L1/	
	L2) 7 W nominal (GPS L1/L2 + GLONASS L1/L2 + BeiDou B1/B2 + L-band)	
Current Consumption:	0.44 A nominal (GPS L1/L2 + GLONASS L1/	
Power	L2) 0.51 A nominal (GPS L1/L2 + GLONASS L1/ L2 + BeiDou B1/B2 + L-band)	
Power Isolation: Reverse Polarity Protection: Antenna	500 ∨	
	Yes	
Voltage: Antenna Short	5 VDC maximum 60mA	
Circuit Protection: Antenna Gain	Yes	
Input Range:	10 to 40 dB	
Environmental Operating		
Temperature: Storage	-30°C to + 70°C (-22°F to + 158°F)	
Temperature: Humidity: Mechanical	-40°C to + 85°C (-40°F to + 185°F) 95% non-condensing	
Shock:	EP455 Section 5.14.1 Operational (when mounted in an enclosure with screw mounting holes utilized) EP455	
Vibration: EMC:	Section 5.15.1 Random CE (IEC 60945 Emissions and Immunity) FCC Part 15, Subpart B CISPR22	
Enclosure:	IP66 (IEC 60529)	
Mechanical Dimensions:	20.2 L x 12.0 W x 7.5 H (cm) 8.0 L x 4.7 W x3.0 H (in)	
Weight: Status Indications	1.1 kg (2.5 lbs.)	
(LED): Power Switch:	Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock, L-band DGNSS lock Front panel soft switch	
Power/Data Power Connector: Power Connector: Data Connector: Antenna	9-pin ODU metal circular 2-pin ODU metal circular DB9 (sealed)	
Connectors:	2 TNC (female)	
Aiding Devices Gyro:	Provides heading smoothing with GNSS. Drift rate is 1° per minute in heading for periods up to 3 minute when loss of GNSS has occurred ⁴	
Tilt Sensors:	Provide pitch, roll data, assist in fast start- up and heading reacquisition	
ionospheric activity.	nvironment, number of satellites in view, satellite geometry, no SA, and	
 Depends on multipath en (for differential services), Based on a 40 second tir 	nvironment, number of satellites in view, satellite geometry, baseline length and ionospheric activity. me constant istrance measured when the product is placed in the vicinity of the steering.	

 Based on a 40 second time constant
 This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation.

separation. Hemisphere GNSS proprietary CMR and CMR+ do not cover proprietary messages outside of the typical standard

Hemisphere GNSS

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