Vector[™] H301 GNSS Compass Board

Advanced Heading & Positioning with Athena[™]

- Extremely accurate heading with short baselines
- L1/L2 GPS/GLONASS/BeiDou RTK
 capable
- Small form factor
- Fast RTK acquisition and reacquisition times
- Excellent coasting performance
- 5 cm rms RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection



Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vector H301 is our smallest multi-frequency, multi-GNSS heading and positioning board.

The Vector H301 utilizes dual antenna ports to create a series of additional capabilities to Eclipse[™] Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, RTK-enabled heave, low power consumption, and precise timing.

Integrate the Vector H301 into your applications to experience exceptional performance, flexibility and cost savings. This incredible GNSS board uses advanced multipath mitigation techniques and offers full scalability and expandability from L1 GPS to L1/L2 GPS/GLONASS/ BeiDou RTK performance.



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Vector H301 GNSS Compass Board

GNSS Receiver Specifications

Receiver Type: Signals Received: Channels: GPS Sensitivity: SBAS Tracking: Update Rate: Horizontal Accuracy: RTK: ^{1,2} SBAS (WAAS): ¹ Autonomous, no SA: ¹ Heading Accuracy:

Pitch / Roll Accuracy: Heave Accuracy: Timing (1PPS) Accuracy: Rate of Turn: Cold Start:

Warm Start: Hot Start:

Heading Fix: Antenna Input Impedance: Maximum Speed: Maximum Altitude:

Communications Serial Ports:

Baud Rates: Correction I/O Protocol: Data I/O Protocol: Timing Output:

Event Marker Input:

Multi-frequency, multi-GNSS RTK GPS, GLONASS, and BeiDou 744 -142 dBm 3-channel, parallel tracking 10 Hz standard, 20 Hz optional 2DRMS (95%) RMS (67%) 8 mm + 1 ppm 15 mm + 2 ppm 0.50 m 0.25 m 1.20 m 2.40 m < 0.2° rms @ 0.5 m antenna separation < 0.1° rms @ 1.0 m antenna separation < 0.05° rms @ 2.0 m antenna separation < 0.02° rms @ 5.0 m antenna separation < 1° rms 30 cm rms (DGPS) ³, 5 cm rms (RTK) ³ 20 ns 100°/s maximum < 60 s typical (no almanac, ephemeris, position or RTC) < 30 s typical (almanac and RTC) < 5 s typical (no almanac, ephemeris, position or RTC) < 20 s typical (Hot Start) 50 **Ω** 1,850 kph (999 kts) 18,288 m (60,000 ft)

4 full-duplex 3.3 V CMOS (3 main serial ports, 1 differential-only port), 1 USB Host, 1 USB Device 4800 - 115200 L-Diff^{M 4}, RTCM v2.3 (DGPS), RTCM v3 (RTK) NMEA 0183, Crescent binary ⁴, L-Dif ⁴ 1PPS, CMOS, active low, falling edge sync, 10 k Ω , 10 pF load CMOS, active low, falling edge sync, 10 k Ω , 10 pF load

Power

Input Voltage: Power Consumption:

Current Consumption:

Antenna Voltage: Antenna Short Circuit Protection: Antenna Gain Input Range: Antenna Input Impedance:

Environmental

Operating Temperature: Storage Temperature: Humidity:

Mechanical Dimensions:

Weight: Status Indication (LED):

Power/Data Connector: Antenna Connectors:

Aiding Devices Gyro:

Tilt Sensors:

3.3 VDC +/- 5% < 4.3 W at 3.3 V (L1/L2 GPS/GLONASS/ BeiDou; gyro) < 1290 mA at 3.3 V (L1/L2 GPS/GLONASS/ BeiDou; gyro) 15 VDC maximum

Yes 10 to 40 dB 50 **Ω**

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when installed in an enclosure)

7.8 L x 7.8 W x 1.6 H (cm) 3.07 L x 3.07 W x 0.63 H (in) 55 g (1.94 oz.) Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock 34-pin male header, 0.08" pitch 2 mm pitch MCX, female, straight

Provides smooth heading, fast heading reacquisition and reliable < 0.5° per minute heading for periods up to 3 minutes when loss of GNSS has occurred Provide pitch and roll data, and assist in fast start-up and reacquisition of heading solution

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

- ² Depends also on baseline length
- ³ Based on a 40 second time constant

⁴Hemisphere GNSS proprietary

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